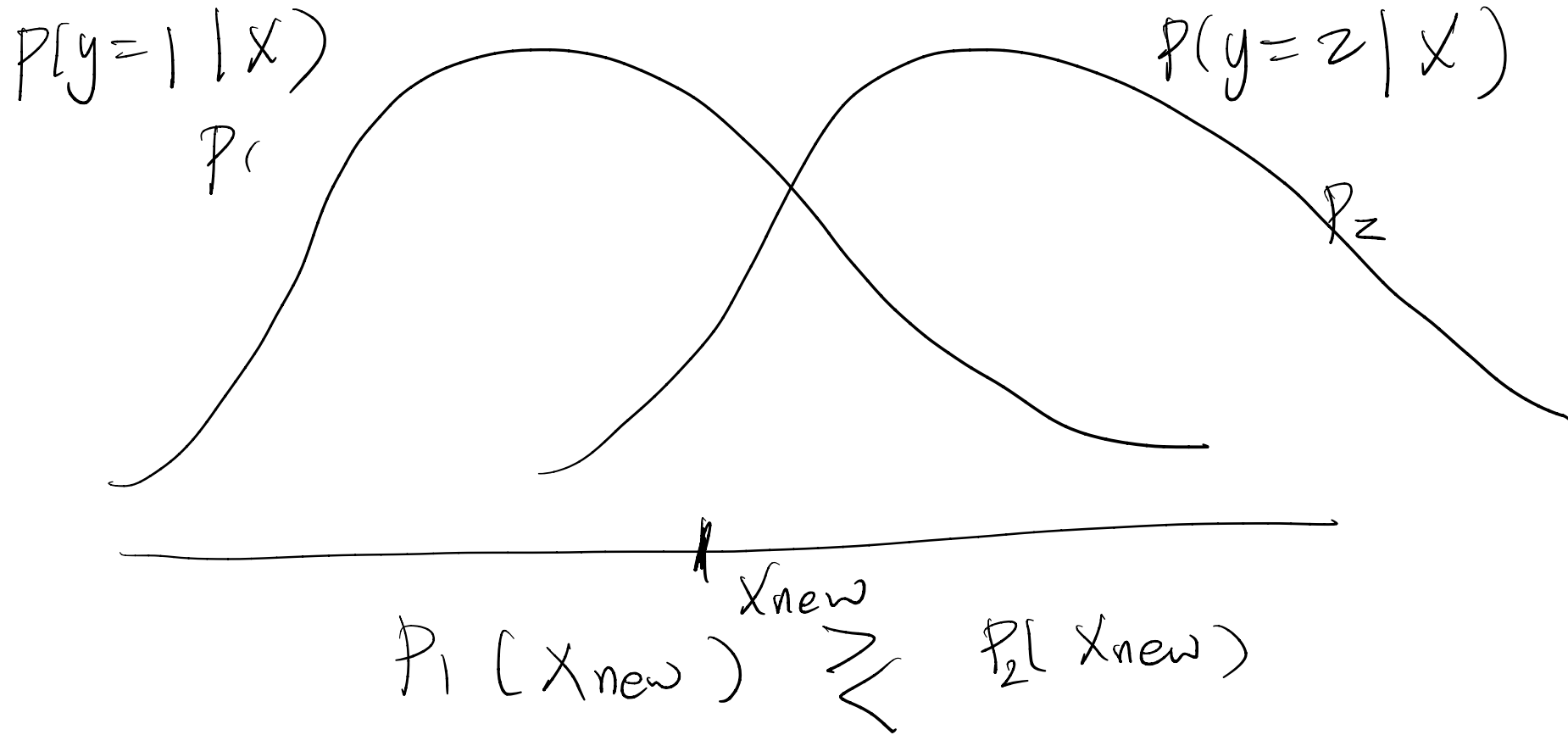
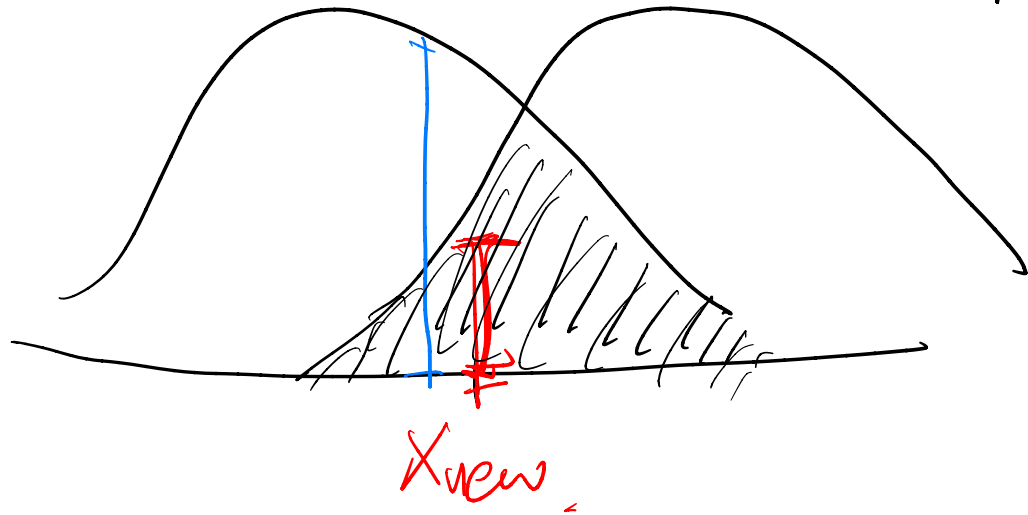


Bayes optimal classifier.



Bayes
error



$$\frac{P_2(x_{\text{new}})}{P_1(x_{\text{new}}) + P_2(x_{\text{new}})}$$

Risk

$$R^* = \int \min \left[\frac{P_1(x)}{P_1(x) + P_2(x)}, \frac{P_2(x)}{P_1(x) + P_2(x)} \right] P(x) dx$$

if we assume $P_1(x) = P_2(x)$

$$P(x) = \frac{P_1(x) + P_2(x)}{2}$$

$$R^* = \frac{1}{2} \int \min [P_1(x), P_2(x)] dx$$

Graphical Models.

$$p(x) = \frac{1}{\sqrt{2\pi}^D \cdot |\Sigma|^{\frac{1}{2}}} \exp\left[-\frac{1}{2} (x-\mu)^T \Sigma^{-1} (x-\mu)\right]$$

parameters: μ, Σ .

$$x \in \mathbb{R}^D$$

$$\mu \in \mathbb{R}^D \quad \begin{pmatrix} \mu_1 \\ \vdots \\ \mu_D \end{pmatrix}$$

$$\Sigma \in \mathbb{R}^{D \times D}$$

$$\begin{bmatrix} \sigma_{11} & & & \\ & \sigma_{22} & & \\ & & \ddots & \\ & & & \sigma_{nn} \end{bmatrix}$$

$$D +$$

$$1+2+\dots+D =$$

$$\boxed{\frac{D(D+1)}{2}}$$

⊕ all elements x_i are independent each other?

$$\mu \in \mathbb{R} \quad \begin{pmatrix} \mu_1 \\ \vdots \\ \mu_D \end{pmatrix} \quad \Sigma = \begin{bmatrix} \sigma_{11} & 0 & 0 & \dots \\ & \ddots & & \\ & & \ddots & \\ & & & \sigma_{nn} \end{bmatrix} \Rightarrow \text{PDF} \Rightarrow \text{PDF}$$

⊕ X_1 and X_2 are independent!

$$p(x) = p(x_1, x_2) = p(x_1) \cdot p(x_2)$$

$$\mu \in \mathbb{R} \quad \Sigma = \begin{bmatrix} \boxed{D_1} & \text{shaded} \\ \text{shaded} & D_2 \end{bmatrix} \quad \frac{p_1(p_1+1) + p_2(p_2+1)}{2}$$

Fundamental Idea: Chain Rule.

$$p(x) = p(x_1, x_2, \dots, x_D)$$

$$= p(x_1) \underbrace{p(x_2, x_3, \dots, x_D | x_1)}$$

$$= p(x_1) p(x_2 | x_1) p(x_3, x_4, \dots, x_D | x_2, x_1),$$

$$= \begin{matrix} \vdots \\ p(x_1) p(x_2 | x_1) p(x_3 | x_1, x_2) p(\bigwedge_{x_4 \dots x_D} (x_1, x_2, x_3)) \end{matrix}$$

If $x_1, x_2, \dots, x_D$ are mutually independent.

$$P(X) \stackrel{(1)}{=} P(x_1) P(x_2|x_1) P(x_3|x_1, x_2) \dots P(x_D|x_1, \dots, x_{D-1})$$

(as x_1 and x_2 are independent.

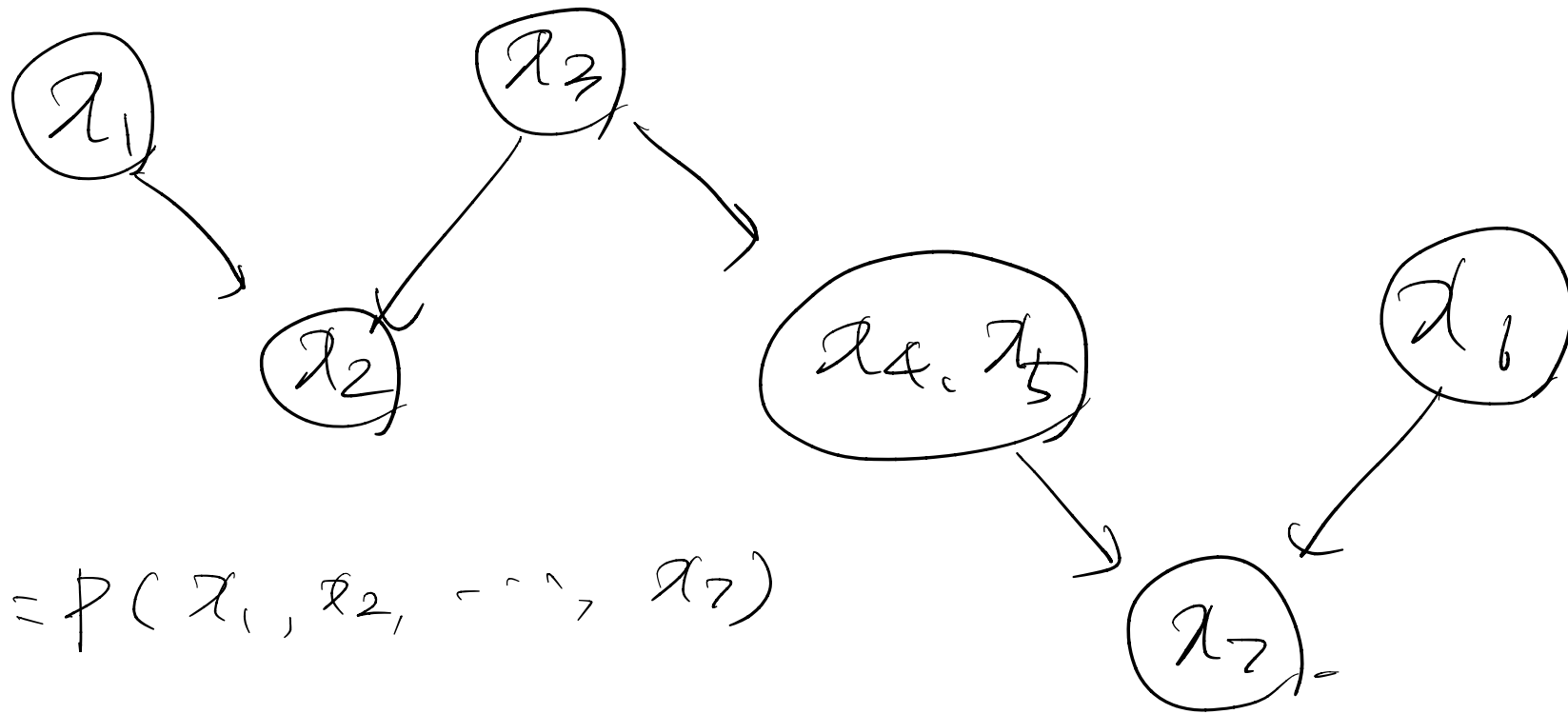
$$P(x_1, x_2) = P(x_1) P(x_2)$$

$$P(x_2|x_1) = \frac{P(x_1, x_2)}{P(x_1)} = P(x_2)$$

$$\stackrel{(2)}{=} P(x_1) P(x_2) P(x_3) \dots P(x_D)$$

Directed Graphical Model (= Bayes Network).

"If a causality graph is given"

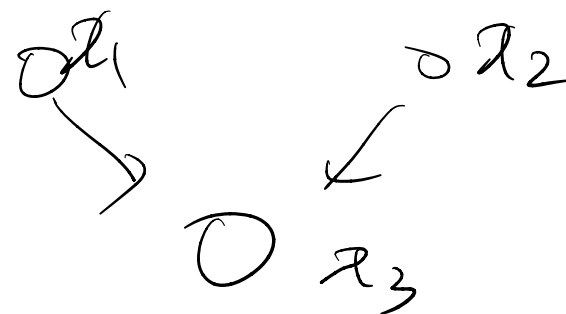
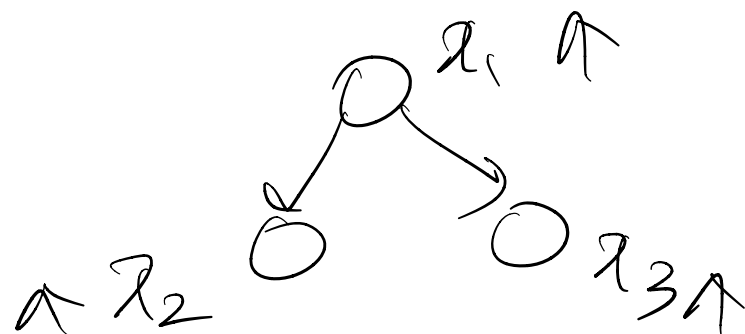
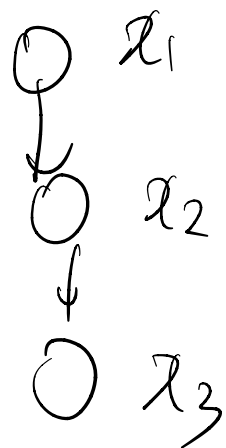


$$p(x) = p(x_1, x_2, \dots, x_7)$$

$$= p(x_1) p(x_3) p(x_2 | x_1, x_3)$$

$$\cdot p(x_4, x_5 | x_3) p(x_6) p(x_7 | x_4, x_5, x_6)$$

↑ "Independencies" (D-separation)



$$x_1 \perp\!\!\!\perp x_3 \mid x_2$$

$$x_2 \perp\!\!\!\perp x_3 \mid x_1$$

$$\begin{cases} x_1 \perp\!\!\!\perp x_2 \\ x_1 \not\perp\!\!\!\perp x_2 \mid x_3 \end{cases}$$

