

25. 9.11

N

x_1	x_2	x_3	x_4	y

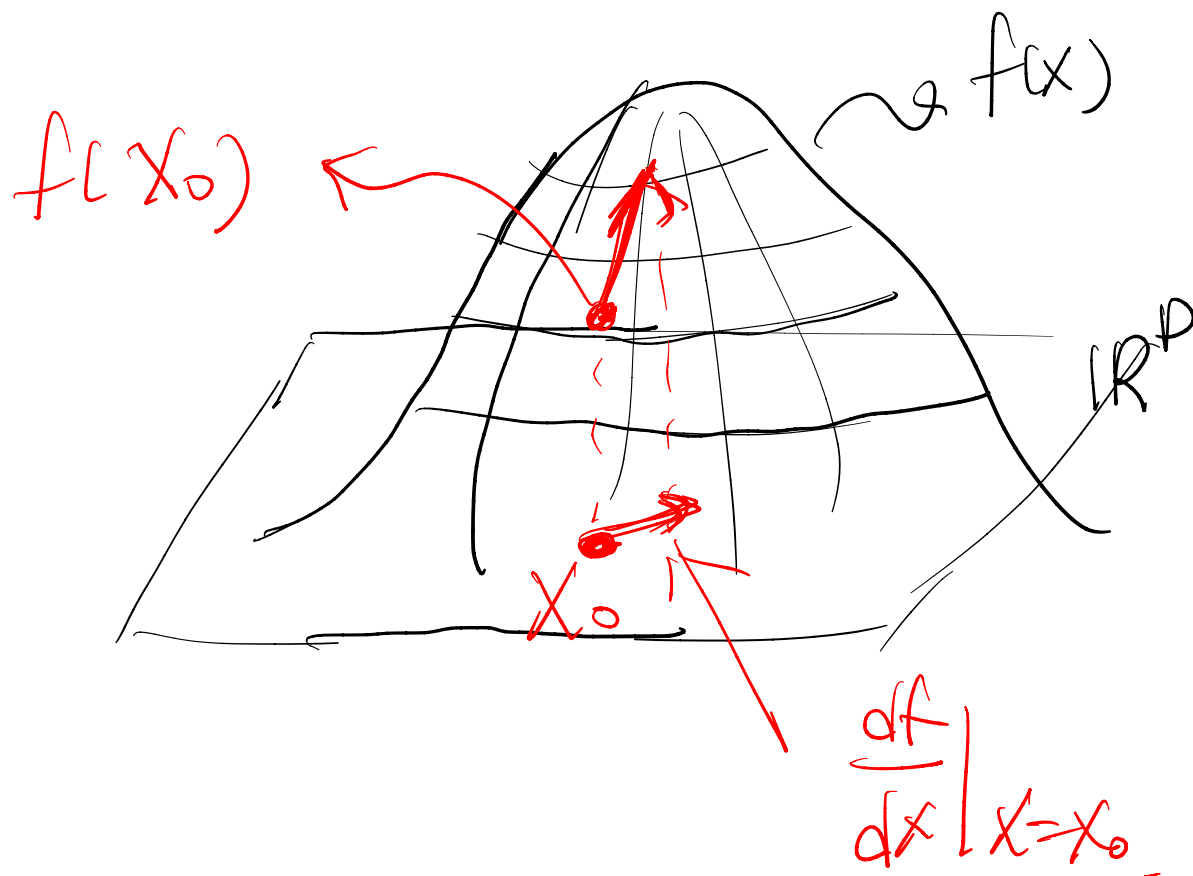
$$f(x) = y = ax_1 + bx_2 + cx_3 + dx_4 + e.$$

$$\underbrace{y - \hat{y}}_{\text{residual}} = \|y - f(x)\|$$

Derivative w.r.t a vector (a matrix).

$$f: \mathbb{R}^D \rightarrow \mathbb{R}$$
$$X \mapsto y$$

$$X = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_D \end{pmatrix} \in \mathbb{R}^D \text{ year.}$$



$$\frac{df}{dx} \approx \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_D} \end{pmatrix} \in \mathbb{R}^D$$

$$f(x) = ax$$

$$\frac{df}{dx} = a$$

$$f(x) = x^2$$

$$\frac{df}{dx} = 2x$$

$$x \in \mathbb{R}$$

$$f(x) = w^T x$$

$$\frac{df}{dx} = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_D} \end{pmatrix}$$

$$= \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_D \end{pmatrix} = w$$

$$w \in \mathbb{R}^D$$

$$x \in \mathbb{R}^D$$

$$f(x) = x^2 = \underbrace{x^T x} = (x_1 \ x_2 \ \dots \ x_p) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{pmatrix}$$

$$\frac{df}{dx} = 2x.$$

$$f(x) = \underbrace{(w^T x - 1)}_y^2$$

$$\frac{df}{dx} = 2(w^T x - 1) \cdot w$$

$$f(x) = \underbrace{y^2} \quad \underbrace{y = w^T x - 1}$$

$$\frac{df}{dy} = 2y, \quad \frac{dy}{dx} = w$$

$$y = f(g(x))$$

$$\frac{dy}{dx} = f'(g(x)) \cdot g'(x)$$

Ex) $f(x) = W^T X = \sum_{i=1}^D w_i x_i = \underbrace{w_1 x_1 + \dots + w_D x_D}$

$$W = \begin{pmatrix} w_1 \\ \vdots \\ w_D \end{pmatrix} \quad X = \begin{pmatrix} x_1 \\ \vdots \\ x_D \end{pmatrix}$$

$$\left[\frac{df}{dx} \right]_i = \frac{\partial f}{\partial x_i} = w_i,$$

$$\frac{df}{dx} = \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_D \end{bmatrix} = w \in \mathbb{R}^D.$$

$$\text{Ex)} \quad f(w) = \sum_{i=1}^N (w^T x_i - b)^2 \quad w, x_1, \dots, x_N \in \mathbb{R}^D$$

$$= (w^T x_1 - b)^2 + (w^T x_2 - b)^2 + \dots + (w^T x_N - b)^2 \quad b \in \mathbb{R}$$

$$= \sum_{i=1}^N \left(\sum_{j=1}^D w_j x_{ij} - b \right)^2$$

$$x_i = \begin{pmatrix} x_{i1} \\ x_{i2} \\ \vdots \\ x_{iD} \end{pmatrix}$$

$$\frac{df}{dw} = \begin{pmatrix} \sum_{i=1}^N 2 \left(\sum_{j=1}^D w_j x_{ij} - b \right) x_{i1} \\ \sum_{i=1}^N 2 \left(\sum_{j=1}^D w_j x_{ij} - b \right) x_{i2} \\ \vdots \\ \sum_{i=1}^N 2 \left(\sum_{j=1}^D w_j x_{ij} - b \right) x_{iD} \end{pmatrix} = \sum_{i=1}^N 2 (w^T x_i - b) x_i$$

$$\left\{ \begin{array}{l} f(x) = w^T x \end{array} \right. \Rightarrow \frac{df}{dx} = w \in \mathbb{R}^D.$$

$$\left\{ \begin{array}{l} f(x) = x^2 \end{array} \right. \Rightarrow \frac{df}{dx} = 2x \in \mathbb{R}^D.$$

$$\left\{ \begin{array}{l} f(x) = (w^T x - 1)^2 \end{array} \right. \Rightarrow \frac{df}{dx} = 2(w^T x - 1) w.$$

$$f(B) = \text{Tr}[ABC] \Rightarrow \frac{df}{dB} = ? \in \mathbb{R}^{D \times D}.$$

$$B \in \mathbb{R}^{D \times D}$$

$$\left[\frac{df}{dB} \right]_{ij} = \frac{\partial f}{\partial B_{ij}}$$

$$\text{tr}[M] = \sum_{i=1}^D M_{ii}$$

$$M = \begin{bmatrix} \textcircled{M_{11}} & M_{12} & \dots & M_{1D} \\ \vdots & \textcircled{M_{22}} & & \vdots \\ \vdots & & & \vdots \\ M_{D1} & M_{D2} & \dots & \textcircled{M_{DD}} \end{bmatrix}$$

$$\underline{\text{tr}[AB]} = \sum_l \left[\begin{array}{c} \text{---} A \text{---} \\ \text{---} \end{array} \right] \left[\begin{array}{c} m \\ \text{---} B \text{---} \\ \text{---} \end{array} \right] = \sum_{k=1}^D A_{lk} B_{km}$$

$$\text{tr}[ABC] = \sum_l \left[\begin{array}{c} \text{---} AB \text{---} \\ \text{---} \end{array} \right] \left[\begin{array}{c} n \\ \text{---} C \text{---} \\ \text{---} \end{array} \right] = \sum_{m=1}^D \sum_{k=1}^D A_{lk} B_{km} C_{ml}$$

$$\text{tr}[ABC] = \sum_{l=1}^D \sum_{m=1}^D \sum_{k=1}^D A_{lk} B_{km} C_{ml}$$

$$f(B) = \text{Tr}[ABC] = \sum_l \sum_m \sum_k A_{lk} B_{km} C_{ml}$$

$\uparrow \quad \uparrow$
 $p \quad q$

$$\left[\frac{df}{dB} \right]_{pq} = \frac{\partial f}{\partial B_{pq}} = \sum_{l=1}^P A_{lp} C_{ql}$$

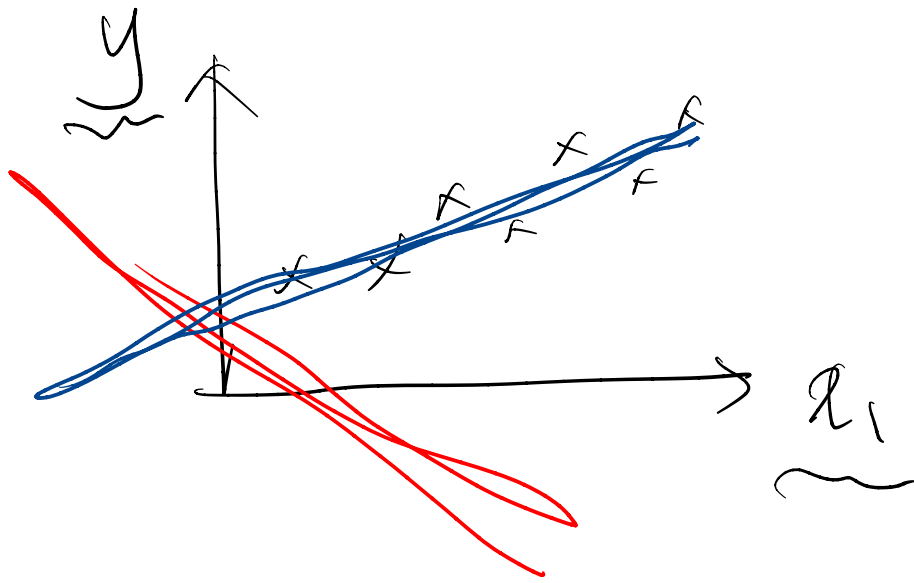
p q

$$\left[\frac{df}{dB} \right]$$

$$= \sum_{l=1}^P \underline{A_{lp}^T C_{ql}^T}$$

$$= [A^T C^T]_{pq}$$

$$\frac{df}{dB} = A^T C^T \in \mathbb{R}^{P \times P}$$



$$f(x) = \underline{w_1 x_1 + w_2 x_2} \\ + w_3 x_3 + w_4 x_4 \\ + b$$

$$\underset{w, b}{\operatorname{argmin}} \underbrace{\|f(x) - y\|^2}$$

